CENTRO DE INVESTIGACIÓN Y DE ESTUDIOS AVANZADOS DEL IPN

El *Departamento de Control Automático*

invita cordialmente a su

Seminario Departamental

Inverse Model Approach to Disturbances Rejection and Decoupling Controller Design

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Planta Baja del Depto. de Control Automático, CINVESTAV-IPN, Unidad Zacatenco, D.F.

Abstract :
Inverse model approach to unmeasurable disturbances rejection is considered. Both disturbances observer and compensator as well as disturbances decoupling controller design method are developed based on UIO-theory.